

# Notes on hydrostatic forces on plane surfaces

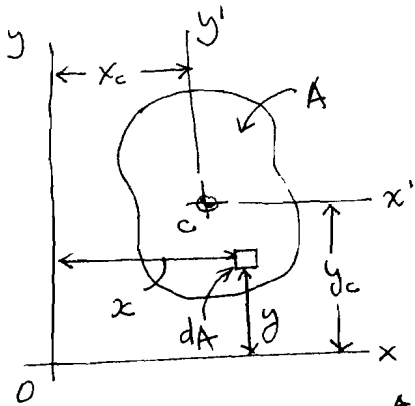


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for  
CEE 3500 – *CEE Fluid Mechanics*

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Area properties - show up in calculations related to forces on plane surfaces



First moment with respect to:

x-axis:  $M_x^A = \int_A y dA = y_c A$

y-axis:  $M_y^A = \int_A x dA = x_c A$

with area,  $A = \int_A dA$ , the coordinates of the centroid C

are:  $x_c = \frac{M_y^A}{A} = \frac{\int x dA}{\int dA}$  and  $y_c = \frac{M_x^A}{A} = \frac{\int y dA}{\int dA}$

(1)

Moments of inertia with respect to:

x-axis:  $I_x = \int_A y^2 dA$

y-axis:  $I_y = \int_A x^2 dA$

origin (polar moment of inertia):

$I_o = I_x + I_y = \int (x^2 + y^2) dA = \int r^2 dA$

with  $r^2 = x^2 + y^2$

Associated with the moments of inertia are the radii of gyration:

$k_x = \sqrt{\frac{I_x}{A}}$

$k_y = \sqrt{\frac{I_y}{A}}$

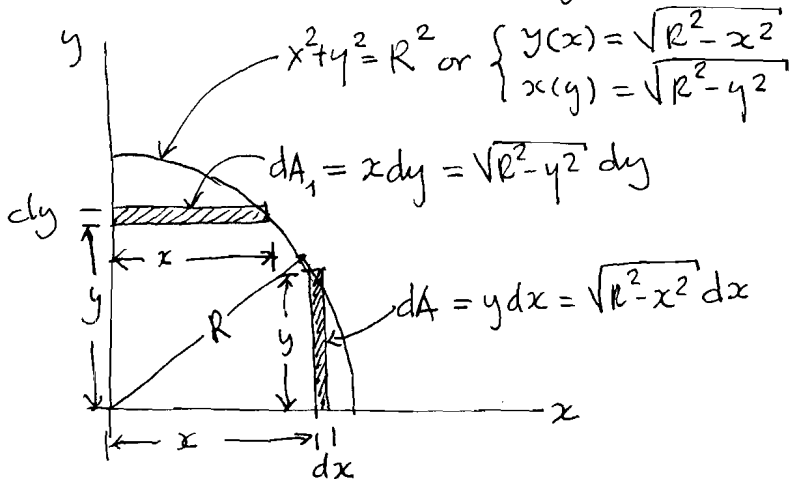
$k_o = \sqrt{\frac{I_o}{A}}$

PARALLEL AXES THEOREM

$I_x = I_{x'} + y_c^2 A$ ,  $I_o = I_{o'} + r_c^2 A$  with  
 $I_y = I_{y'} + x_c^2 A$   $r_c^2 = x_c^2 + y_c^2$

primed quantities referred to centroidal axes  $x', y'$

Calculations using elementary area strips



AREA:  $A = \int dA_1$  or  $\int dA_2$

$A = \int_{y=0}^{y=R} \sqrt{R^2 - y^2} dy = \int_{\theta=0}^{\theta=\pi/2} R \cos \theta \cdot R \cos \theta d\theta$

change of variable  
 $y = R \sin \theta \Rightarrow \begin{cases} y=0 \rightarrow \theta=0 \\ y=R \rightarrow \theta=\pi/2 \end{cases}$   
 $dy = R \cos \theta d\theta$   
 $\sqrt{R^2 - y^2} = R \cos \theta$

$A = R^2 \int_0^{\pi/2} \cos^2 \theta d\theta = \frac{R^2}{2} \int_0^{\pi/2} (1 + \cos 2\theta) d\theta = \frac{R^2}{2} \left[ \int_0^{\pi/2} d\theta + \int_0^{\pi/2} \cos 2\theta d\theta \right] = \frac{R^2}{2} \left[ \theta \Big|_0^{\pi/2} + \left( \frac{1}{2} \sin 2\theta \right) \Big|_0^{\pi/2} \right]$

$A = \frac{R^2}{2} \left[ \frac{\pi}{2} + \frac{1}{2}(0-0) \right] = \frac{\pi R^2}{4}$  ← we could have found this out since it is 1/4 of the area of a circle ( $\pi R^2$ )

## First moments of area

$$M_x^A = \int_A y dA_1 = \int_{y=0}^{y=R} y \sqrt{R^2 - y^2} dy = \int_0^{\pi/2} R \sin \theta \cdot R \cos \theta \cdot R \cos \theta d\theta = R^3 \int_0^{\pi/2} \sin \theta \cos^2 \theta d\theta = R^3 \int_1^0 u^2 (-du)$$

CHANGE OF VARIABLE:

$$u = \cos \theta \rightarrow \begin{cases} \theta = 0, u = 1 \\ \theta = \pi/2, u = 0 \end{cases}$$

$$du = -\sin \theta d\theta$$

$$= -R^3 \frac{u^3}{3} \Big|_1^0 = -\frac{R^3}{3} (0 - 1) = \frac{R^3}{3} \quad (2)$$

similarly,  $M_y^A = \int_A x dA_2 = \int_{x=0}^{x=R} x \sqrt{R^2 - x^2} dx = R^3/3$  (use  $x = R \sin \theta$ )

Thus, centroidal coordinates:

$$x_c = \frac{M_y^A}{A} = \frac{R^3/3}{\pi R^2/4} = \frac{4R}{3\pi}, \quad y_c = \frac{M_x^A}{A} = \frac{4R}{3\pi}$$

## Moments of inertia

$$I_x = \int y^2 dA_1 = \int_{y=0}^{y=R} y^2 \sqrt{R^2 - y^2} dy = \int_{\theta=0}^{\theta=\pi/2} R^2 \sin^2 \theta \cdot R \cos \theta \cdot R \cos \theta d\theta = R^4 \int_0^{\pi/2} \sin^2 \theta \cos^2 \theta d\theta$$

use  $\begin{cases} \sin \theta \cos \theta = \frac{1}{2} \sin 2\theta \\ \sin^2 2\theta = \frac{1}{2} (1 - \cos 4\theta) \end{cases} \Rightarrow I_x = \frac{R^4}{4} \int_0^{\pi/2} \sin^2 2\theta d\theta = \frac{R^4}{8} \int_0^{\pi/2} (1 - \cos 4\theta) d\theta$

$$= \frac{R^4}{8} \left[ \int_0^{\pi/2} d\theta - \int_0^{\pi/2} \cos 4\theta d\theta \right] = \frac{R^4}{8} \left[ \theta \Big|_0^{\pi/2} - \frac{1}{4} \sin(4\theta) \Big|_0^{\pi/2} \right]$$

$$I_x = \frac{R^4}{8} \left[ \frac{\pi}{2} - \frac{1}{4} (0 - 0) \right] = \frac{\pi R^4}{16} = \frac{\pi (D/2)^4}{16} = \frac{\pi D^4}{16 \times 16} = \frac{\pi D^4}{256}$$

$R = \text{radius}$   
 $D = 2R = \text{diameter}$

similarly  $I_y = \int x^2 dA_2 = \int_{x=0}^{x=R} x^2 \sqrt{R^2 - x^2} dx = \frac{\pi R^4}{16} = \frac{\pi D^4}{256}$

## radii of gyration

$$k_x = \sqrt{\frac{I_x}{A}} = \sqrt{\frac{\pi R^4/16}{\pi R^2/4}} = \sqrt{R^2 \cdot \frac{4}{16}} = \sqrt{\frac{R^2}{4}} = \frac{R}{2}$$

$$k_y = \sqrt{\frac{I_y}{A}} = \sqrt{\frac{\pi R^4/16}{\pi R^2/4}} = \frac{R}{2}$$

$$A = \int_0^R \sqrt{R^2 - y^2} dy \quad (1)$$

$$M_x^A = \int_0^R y \sqrt{R^2 - y^2} dy$$

$$I_x = \int_0^R y^2 \sqrt{R^2 - y^2} dy$$

Calculating these integrals with the HP49G+

(1)  $\boxed{\rightarrow} \boxed{EQW} \boxed{\rightarrow} \boxed{-} \boxed{0} \boxed{\rightarrow} \boxed{ALPHA} \boxed{R} \boxed{\rightarrow} \boxed{\sqrt{x}} \boxed{ALPHA} \boxed{R} \boxed{y^2} \boxed{2} \boxed{\Delta} \boxed{\Delta} \boxed{-} \boxed{ALPHA} \boxed{\leftarrow} \boxed{Y} \boxed{y^2} \boxed{2} \boxed{\rightarrow} \boxed{ALPHA} \boxed{\leftarrow} \boxed{Y} \boxed{ENTER} \boxed{ENTER} \Rightarrow \boxed{R^2 \cdot \pi} \boxed{4}$  (3)

(2)  $\boxed{\rightarrow} \boxed{EQW} \boxed{\rightarrow} \boxed{-} \boxed{0} \boxed{\rightarrow} \boxed{ALPHA} \boxed{R} \boxed{\rightarrow} \boxed{ALPHA} \boxed{\leftarrow} \boxed{Y} \boxed{x} \boxed{\sqrt{x}} \boxed{ALPHA} \boxed{R} \boxed{y^2} \boxed{2} \boxed{\Delta} \boxed{\Delta} \boxed{-} \boxed{ALPHA} \boxed{\leftarrow} \boxed{Y} \boxed{y^2} \boxed{2} \boxed{\rightarrow} \boxed{ALPHA} \boxed{\leftarrow} \boxed{Y} \boxed{ENTER} \boxed{ENTER} \boxed{EVAL} \Rightarrow \boxed{\frac{R^2 |R|}{3} = \frac{R^3}{3}}$

(3)  $\boxed{\rightarrow} \boxed{EQW} \boxed{\rightarrow} \boxed{-} \boxed{0} \boxed{\rightarrow} \boxed{ALPHA} \boxed{R} \boxed{\rightarrow} \boxed{ALPHA} \boxed{\leftarrow} \boxed{Y} \boxed{\cancel{y^2}} \boxed{2} \boxed{x} \boxed{\sqrt{x}} \boxed{ALPHA} \boxed{R} \boxed{y^2} \boxed{2} \boxed{\Delta} \boxed{\Delta} \boxed{-} \boxed{ALPHA} \boxed{\leftarrow} \boxed{Y} \boxed{y^2} \boxed{2} \boxed{\rightarrow} \boxed{ALPHA} \boxed{\leftarrow} \boxed{Y} \boxed{ENTER} \boxed{ENTER} \boxed{EVAL} \Rightarrow \boxed{\frac{R^4 \cdot \pi}{16}}$

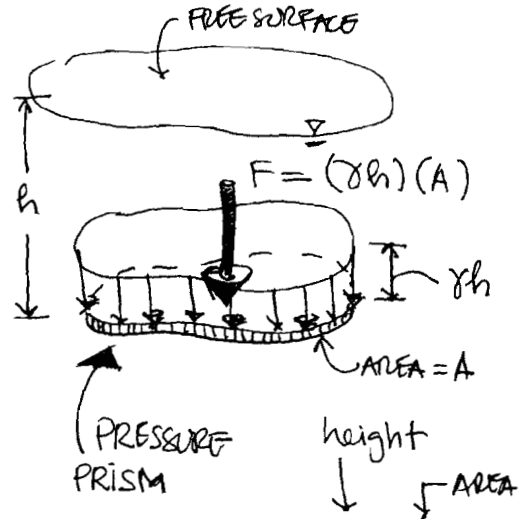
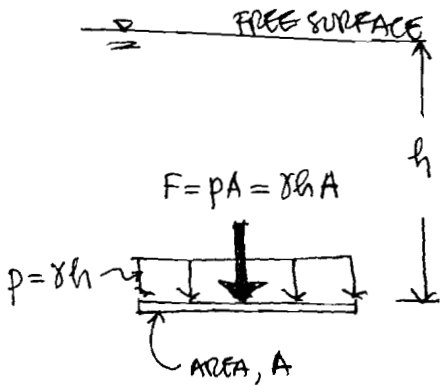
Calculating these integrals using the TI-89 Titanium

(1)  $\boxed{2nd} \boxed{\int} \boxed{2nd} \boxed{\sqrt{}} \boxed{ALPHA} \boxed{\uparrow} \boxed{R} \boxed{\wedge} \boxed{2} \boxed{-} \boxed{Y} \boxed{\wedge} \boxed{2} \boxed{)} \boxed{)} \boxed{Y} \boxed{)} \boxed{0} \boxed{)} \boxed{ALPHA} \boxed{\uparrow} \boxed{R} \boxed{)} \boxed{ENTER} \Rightarrow \frac{\pi \cdot r \cdot |r|}{4}, \text{ should be } \boxed{\frac{\pi R^2}{4}}$

(2)  $\boxed{2nd} \boxed{\int} \boxed{\cancel{y}} \boxed{x} \boxed{2nd} \boxed{\sqrt{}} \boxed{ALPHA} \boxed{\uparrow} \boxed{R} \boxed{\wedge} \boxed{2} \boxed{-} \boxed{Y} \boxed{\wedge} \boxed{2} \boxed{)} \boxed{)} \boxed{Y} \boxed{)} \boxed{0} \boxed{)} \boxed{ALPHA} \boxed{\uparrow} \boxed{R} \boxed{)} \boxed{ENTER} \Rightarrow \frac{|r^3|}{3}, \text{ should be } \boxed{\frac{R^3}{3}}$

(3)  $\boxed{2nd} \boxed{\int} \boxed{y} \boxed{\wedge} \boxed{2} \boxed{x} \boxed{2nd} \boxed{\sqrt{}} \boxed{ALPHA} \boxed{\uparrow} \boxed{R} \boxed{\wedge} \boxed{2} \boxed{-} \boxed{Y} \boxed{\wedge} \boxed{2} \boxed{)} \boxed{)} \boxed{Y} \boxed{)} \boxed{0} \boxed{)} \boxed{ALPHA} \boxed{\uparrow} \boxed{R} \boxed{)} \boxed{ENTER} \Rightarrow \frac{\pi \cdot r \cdot |r^3|}{16}, \text{ should be } \boxed{\frac{\pi R^4}{16}}$

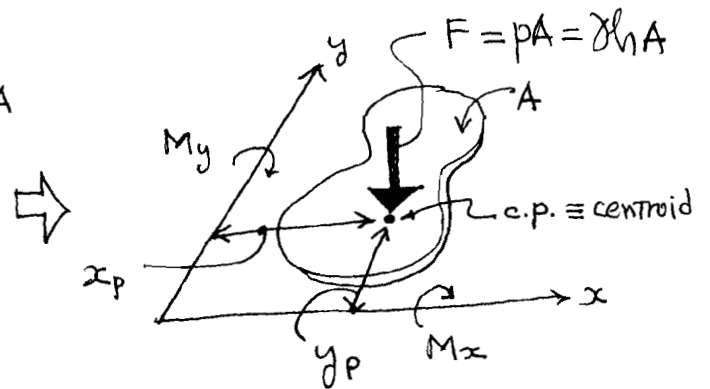
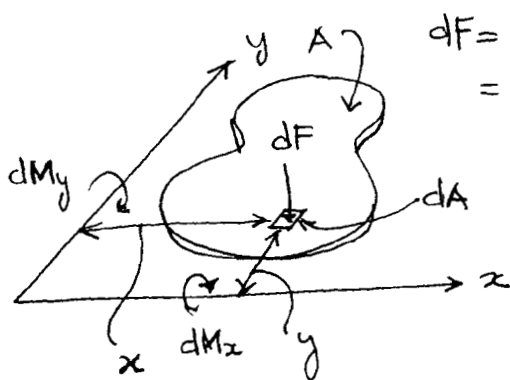
## FORCE ON A HORIZONTAL PLANE AREA



(4)

NOTE: FORCE = volume of pressure prism, in this case  $F = (\gamma h)(A)$

## LOCATION OF FORCE ON A HORIZONTAL PLANE AREA (CENTER OF PRESSURE)



MOMENTS EXERTED BY FORCE  $dF$ :

- about  $x$ :  $dM_x = y \cdot dF$
- about  $y$ :  $dM_y = x \cdot dF$

MOMENT EXERTED BY TOTAL FORCE  $F$ :

- about  $x$ :  $M_x = y_p \cdot F$
- about  $y$ :  $M_y = x_p \cdot F$

The total moments can be calculated as follows:

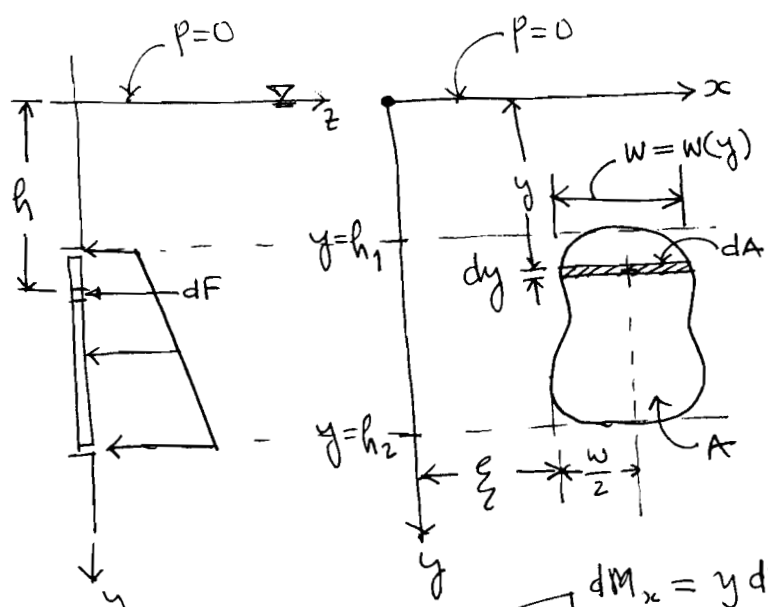
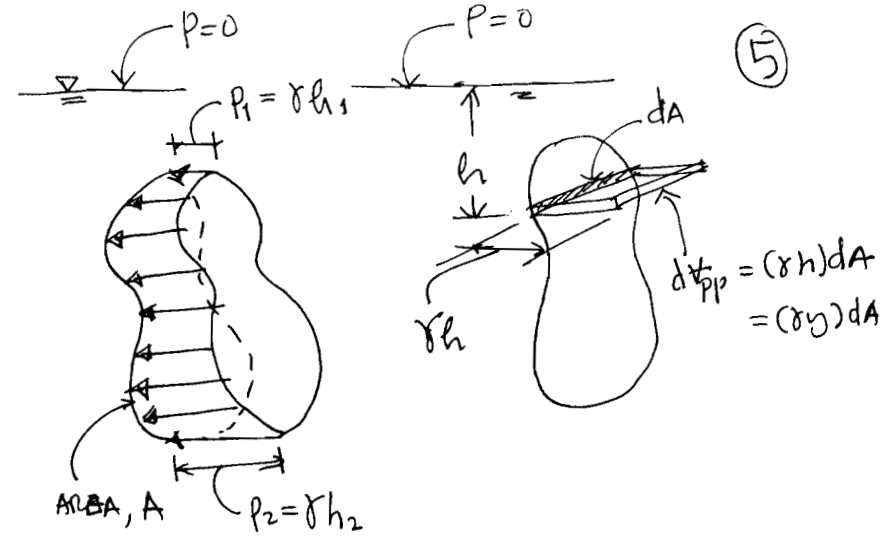
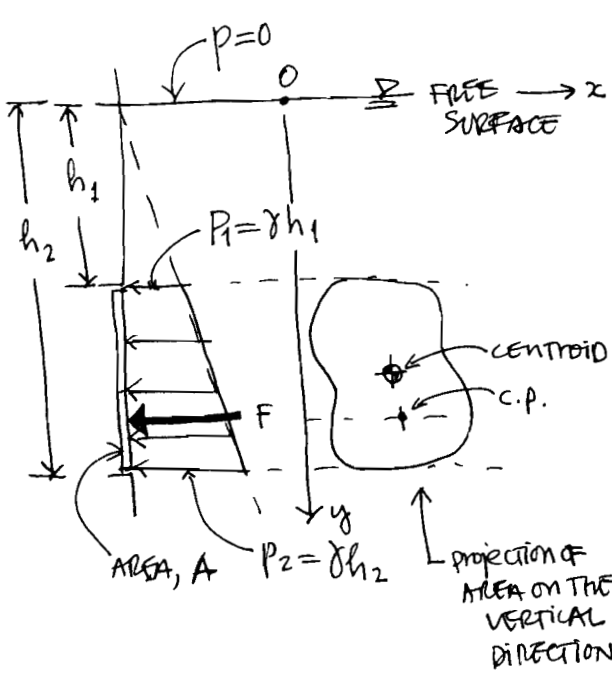
$$M_x = \iint_A dM_x = \iint_A y dF = \iint_A y p dA = \iint_A y \gamma h dA = \gamma h \iint_A y dA$$

$$M_y = \iint_A dM_y = \iint_A x dF = \iint_A x p dA = \iint_A x \gamma h dA = \gamma h \iint_A x dA$$

$$\begin{aligned} \text{Thus, } y_p F &= y_p \gamma h A = \gamma h \iint_A x dA \Rightarrow y_p = \frac{1}{A} \iint_A x dA \\ x_p F &= x_p \gamma h A = \gamma h \iint_A y dA \Rightarrow x_p = \frac{1}{A} \iint_A y dA \end{aligned} \left. \begin{array}{l} \\ \\ \end{array} \right\} \begin{array}{l} \text{CENTROIDAL} \\ \text{COORDINATES} \end{array}$$

FORCE ON A VERTICAL PLANE AREA

(5)



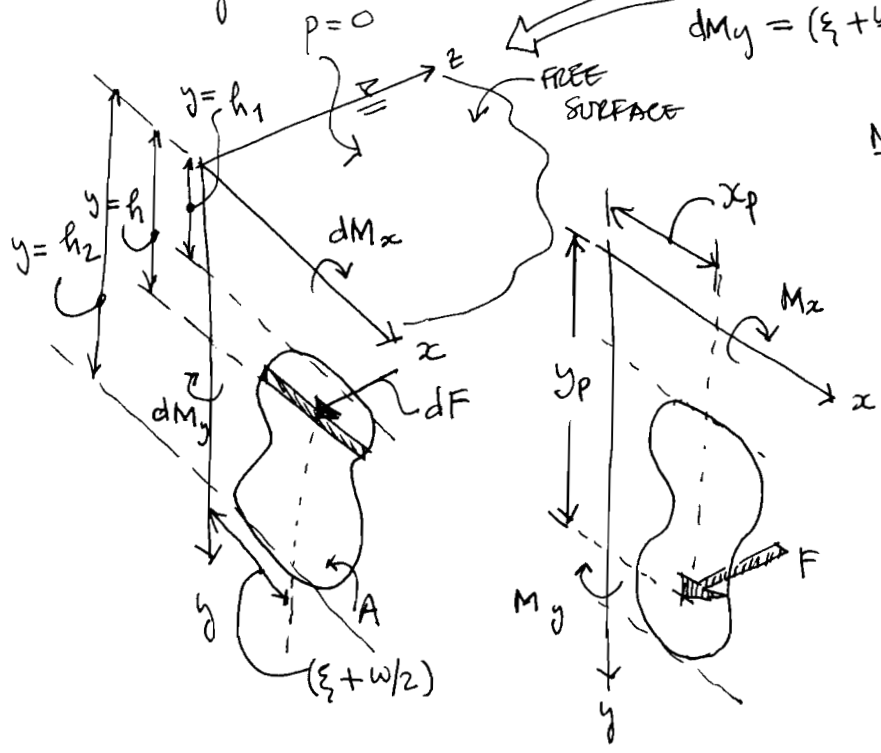
NOTE:  $y = h$   
 AREA ELEMENT,  $dA = w(y) dy$   
 PRESSURE ON  $dA$ ,  $p = \rho h = \rho y$   
 FORCE ON  $dA$ ,  $dF = p dA = \rho y w(y) dy$

TOTAL FORCE ON A:

$$F = \int_{h_1}^{h_2} dF = \int_{h_1}^{h_2} \rho y w(y) dy$$

$$= \rho \int_{h_1}^{h_2} y dA = \int_{h_1}^{h_2} \rho y dA$$

$$= \int_{h_1}^{h_2} dV_{pp} = V_{pp} = \text{volume of pressure prism}$$



MOMENTS:

$$M_x = y_p \cdot F = \int dM_x = \int y dF$$

$$M_y = x_p \cdot F = \int dM_y = \int (\xi + \frac{w}{2}) dF$$

$$M_x = \int_{h_1}^{h_2} y dF = \int_{h_1}^{h_2} y \cdot \rho y w(y) dy$$

$$= \int_{h_1}^{h_2} \rho y^2 dA = y_p \cdot \int_{h_1}^{h_2} \rho y dA$$

(continues in next page)  $\Rightarrow$

since  $\gamma = \text{constant} \Rightarrow$

$$\int_{h_1}^{h_2} \gamma y^2 dA = \gamma y_p \int_{h_1}^{h_2} y dA \Rightarrow I_x = y_c \cdot A \cdot y_p \Rightarrow \boxed{y_p = \frac{I_x}{y_c A}}$$

**PARALLEL-AXES THEOREM**

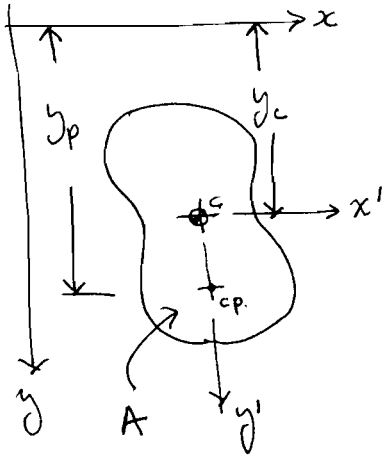
MOMENT OF INERTIA ( $I_x$ ) w.r.t.  $x$

FIRST MOMENT w.r.t.  $x = y_c \cdot A$

$A = \text{AREA}$

$y_c = y$ -coordinate for centroid  
 $I_x = \text{moment of inertia w.r.t. to } x \text{ axis.}$

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Parallel axes theorem indicates that  $I_x = I_{x'} + A y_c^2$

Thus,  $y_p = \frac{I_x}{y_c A} = \frac{I_{x'} + A y_c^2}{y_c A}$

↑ CENTROIDAL MOMENT OF INERTIA w.r.t. to  $x$   
 ↑ DISTANCE BETWEEN AXES

$$\boxed{y_p = y_c + \frac{I_{x'}}{y_c A}}$$

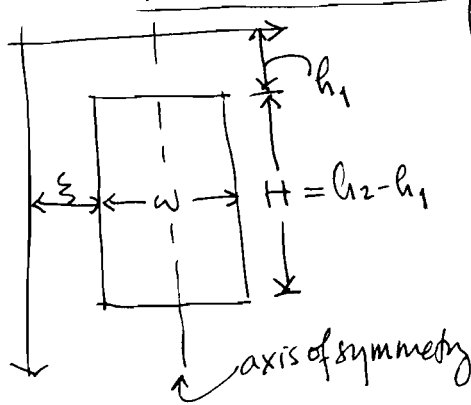
NOTE: since  $I_{x'} > 0, y_c > 0, A > 0 \Rightarrow y_p > y_c$ , i.e., the center of pressure is located below the centroid of the area

From  $M_y = x_p \cdot F = \int_{h_1}^{h_2} (\xi + \frac{w}{2}) dF \Rightarrow x_p \cdot \int_{h_1}^{h_2} \gamma y w(y) dy = \int_{h_1}^{h_2} (\xi + \frac{w}{2}) \gamma y w(y) dy$

$\Rightarrow x_p \cdot \int_{h_1}^{h_2} \underbrace{\gamma y w(y)}_{dA} dy = \int_{h_1}^{h_2} \xi y w dy + \int_{h_1}^{h_2} \gamma \frac{w^2}{2} dy$

$$\boxed{x_p \cdot y_c \cdot A = \int_{h_1}^{h_2} (\xi + \frac{w}{2}) dA}$$

→ specific case:  $w = \text{constant}$  and  $\xi = \text{constant}$



$$\int_{h_1}^{h_2} (\xi + \frac{w}{2}) \gamma w dy = (\xi + \frac{w}{2}) \gamma \int_{h_1}^{h_2} y dy = (\xi + \frac{w}{2}) \gamma \frac{1}{2} (h_2^2 - h_1^2)$$

$$= \omega (\xi + \frac{w}{2}) H (h_2 + h_1)$$

also,  $y_c = h_1 + H/2$

$$x_p (h_1 + H/2) \omega H = \omega (\xi + \frac{w}{2}) \frac{H}{2} (h_2 + h_1)$$

$$x_p = \frac{\xi + w/2}{h_1 + H/2} \cdot (h_2 + h_1) \cdot \frac{1}{2} = \frac{\xi + w/2}{\frac{h_1 + h_2}{2}} \cdot \frac{h_1 + h_2}{2} = \xi + \frac{w}{2}$$

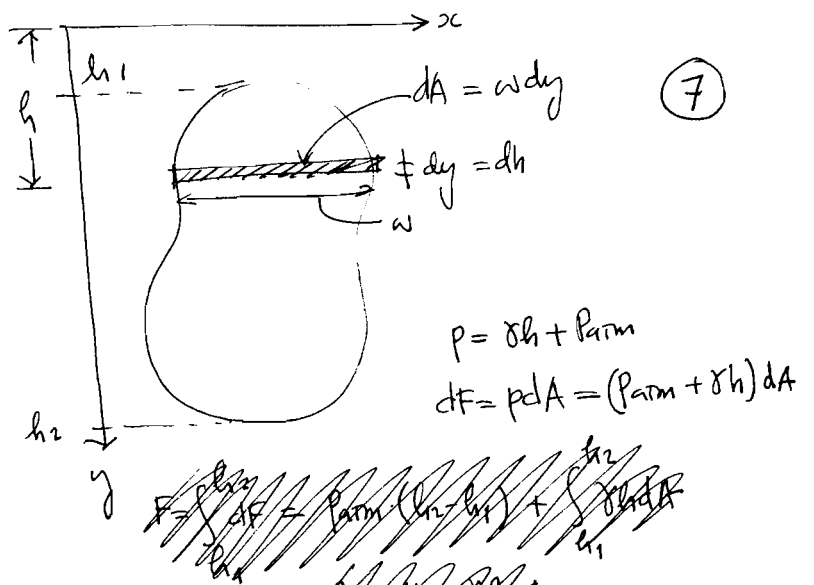
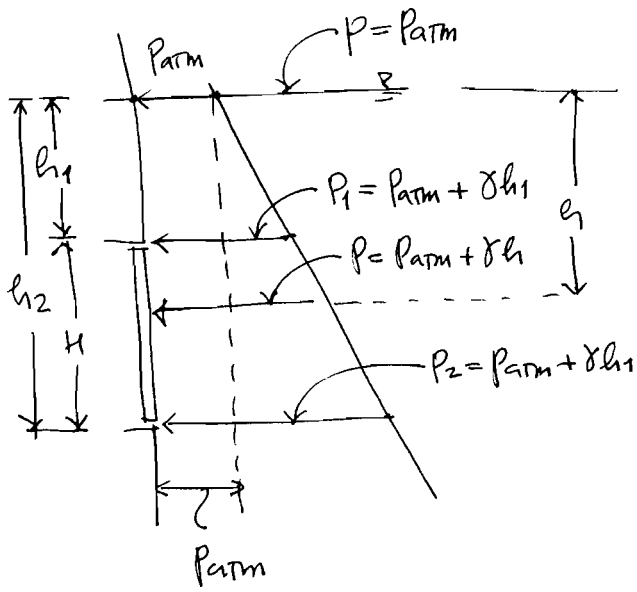
$\Rightarrow \boxed{x_p = x_c}$

↑ similar result for symmetric shapes

NOTE: For symmetric shapes, select  $y$  as the axis of symmetry  $\Rightarrow x_p = x_c = 0$

NOTE:  $F = \gamma \int_{h_1}^{h_2} y dA = \gamma y_c A = \gamma h_c A = p_c A \equiv (\text{pressure at centroid}) \times (\text{area})$

NOTE: we used gage pressure in the previous example. What if we use absolute pressure?



FORCE

$$F = \int_{h_1}^{h_2} dF = \int_{h_1}^{h_2} P_{atm} dA + \int_{h_1}^{h_2} \delta h dA = P_{atm} \int_{h_1}^{h_2} dA + \int_{h_1}^{h_2} \delta h dA$$

$$F = P_{atm} \cdot A + \delta h_c A = (P_{atm} + \delta h_c) A = P_c \cdot A$$

MOMENT WITH RESPECT TO X-AXIS

$$y_p \cdot F = \int_{h_1}^{h_2} y p dA$$

$$y_p (P_{atm} + \delta h_c) A = \int_{h_1}^{h_2} y P_{atm} dA + \int_{h_1}^{h_2} \delta y^2 dA$$

$$y_p A P_{atm} + y_p \delta h_c A = P_{atm} y_c A + \delta I_x, \quad I_x = I_{x_1} + A y_c^2$$

$$y_p A P_{atm} + y_p \delta h_c A = P_{atm} y_c A + \delta I_{x_1} + \delta A y_c^2$$

$$y_p A (P_{atm} + \delta h_c) = P_{atm} y_c A + \delta A y_c^2 + \delta I_{x_1}$$

$$y_p A (P_{atm} + \delta h_c) = (P_{atm} + \delta y_c) A y_c + \delta I_{x_1}$$

$$y_p = y_c + \frac{\delta I_{x_1}}{(P_{atm} + \delta h_c) A} = y_c + \frac{\delta I_{x_1}}{P_c A}$$

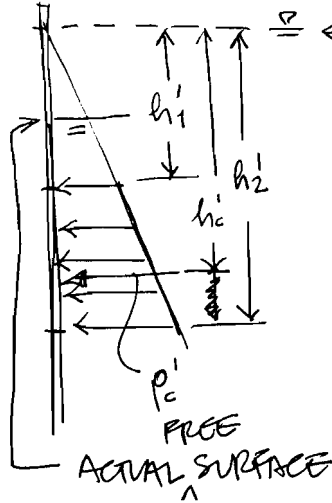
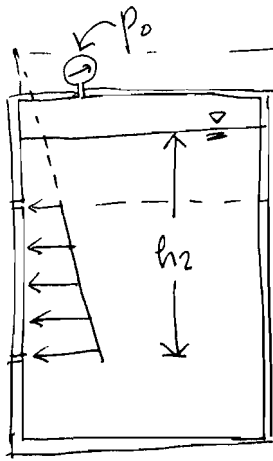
NOTE: these calculations apply also to gage pressure calculations when the free surface pressure is not zero  $\rightarrow$  pressurized vessel

VIRTUAL FREE SURFACE

$h_0 = P_0/\gamma$

$h_1' = h_1 + h_0 = h_1 + \frac{P_0}{\gamma}$   
 $h_2' = h_2 + h_0 = h_2 + \frac{P_0}{\gamma}$

← use depths  $h_1', h_2'$ , etc. measured from the virtual free surface

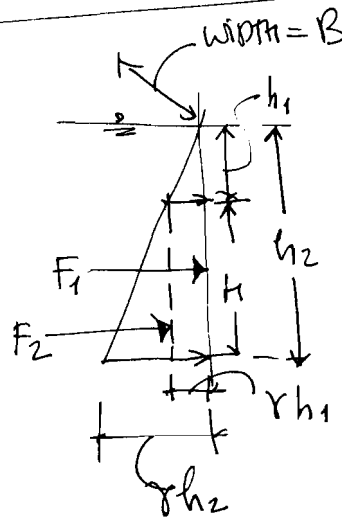
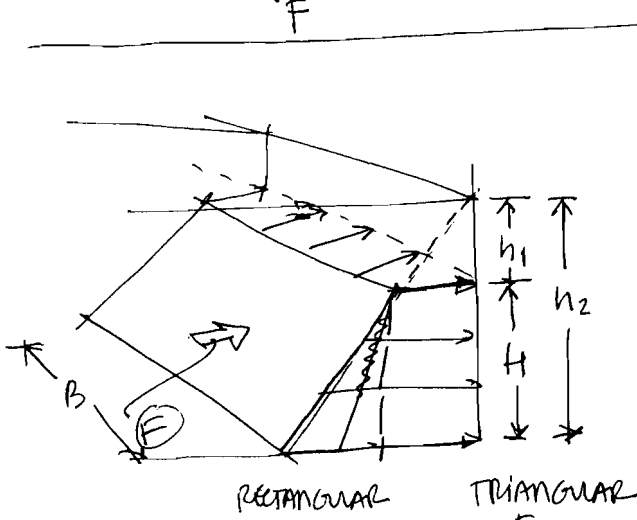
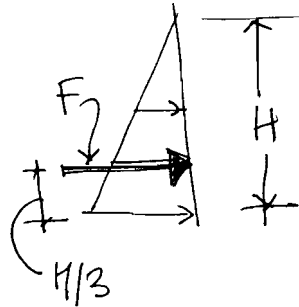
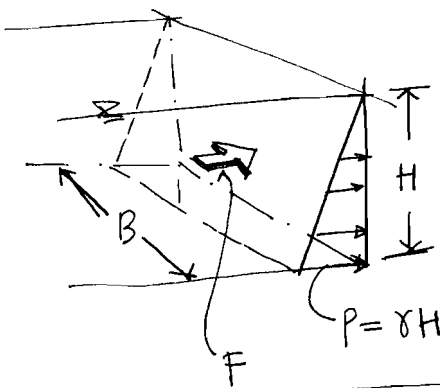


VIRTUAL FREE SURFACE of zero pressure located at  $h_0 = P_0/\gamma$  above (or below, if  $P_0 < 0$ ) of actual free surface

⑧

FORCE = VOLUME OF PRISM OF PRESSURES,  $F = \frac{1}{2} (\delta H)(H)B = \frac{1}{2} \delta B H^2$

~~Force =~~

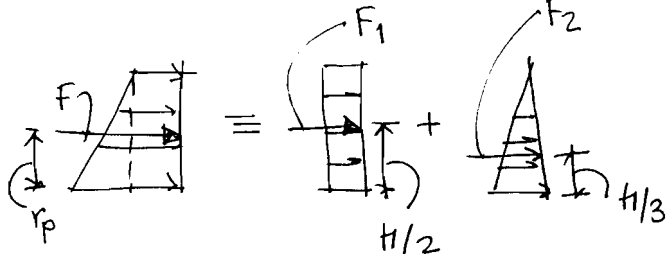


RECTANGULAR CONTRIBUTION  
 $F_1 = \int_0^{h_1} (\delta h_1)(H)(B) = \delta h_1 H B$

TRIANGULAR CONTRIBUTION  
 $F_2 = \frac{1}{2} \delta (h_2 - h_1)(H)(B)$   
 $= \frac{1}{2} \delta H^2 B$

$F = F_1 + F_2 = \delta h_1 H B + \frac{1}{2} \delta H^2 B$

$F = \delta H B (h_1 + \frac{H}{2})$

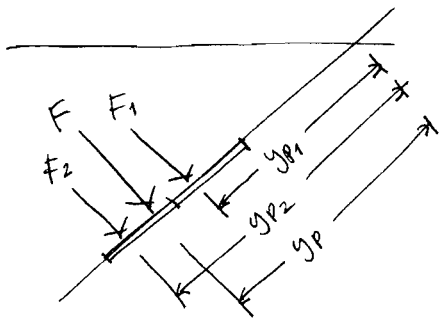


MOMENTS:  $r_p \cdot F = \frac{H}{2} \cdot F_1 + \frac{H}{3} \cdot F_2$

$r_p \cdot (\delta H B \cdot (h_1 + \frac{H}{2})) = \frac{H}{2} \cdot \delta h_1 H B + \frac{H}{3} \cdot \frac{1}{2} \delta H^2 B$

$\delta H B (h_1 + \frac{H}{2}) r_p = \frac{1}{2} \delta H^2 B (h_1 + \frac{H}{3}) \Rightarrow r_p = \frac{H}{2} \cdot \frac{h_1 + \frac{H}{3}}{h_1 + \frac{H}{2}}$





$$F_1 = 198.08 \text{ kN}, y_{P1} = 4.06 \text{ m}$$

$$F_2 = 375.23 \text{ kN}, y_{P2} = 6.07 \text{ m}$$

$$F = 573.13 \text{ kN}, y_P = 5.37 \text{ m}$$

$$y_{c1} = \frac{h_{c1}}{\sin 40^\circ} = \frac{2.96 \text{ m}}{\sin 40^\circ} = 4.04 \text{ m}$$

$$y_{c2} = \frac{h_{c2}}{\sin 40^\circ} = \frac{4.25 \text{ m}}{\sin 40^\circ} = 6.01 \text{ m}$$

$$(I_0)_1 = \frac{\pi D^4}{128} = \frac{\pi \times (1/2)^4}{128} = \frac{\pi \times 4.24^4}{2048} = 0.50 \text{ m}^4$$

$$(I_0)_2 = \frac{bh^3}{12} = \frac{1(1/2)^3}{12} = \frac{H^4}{96} = \frac{4.24^4}{96} = 3.37 \text{ m}^4$$

$$y_{P1} = y_{c1} + \frac{(I_0)_1}{y_{c1} A_1} = 4.04 \text{ m} + \frac{0.50 \text{ m}^4}{4.04 \text{ m} \times 7.06 \text{ m}^2} = 4.06 \text{ m}$$

$$y_{P2} = y_{c2} + \frac{(I_0)_2}{y_{c2} A_2} = 6.01 \text{ m} + \frac{3.37 \text{ m}^4}{6.01 \text{ m} \times 9.00 \text{ m}^2} = 6.07 \text{ m}$$

(10)

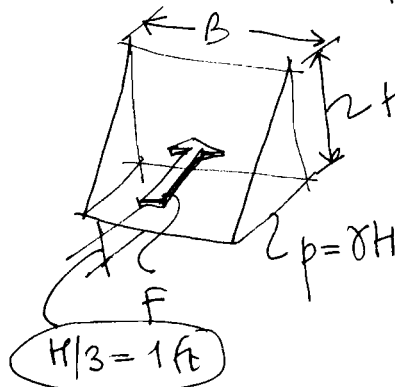
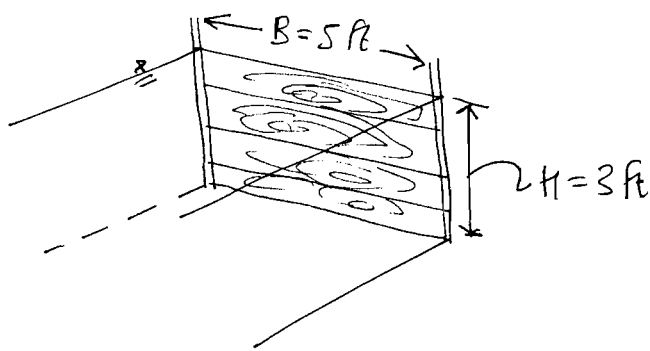
$$y_P \cdot (F_1 + F_2) = y_{P1} F_1 + y_{P2} F_2$$

$$y_P \cdot (573.13 \text{ kN}) = 4.06 \text{ m} \times (198.08 \text{ kN}) + 6.07 \text{ m} \times 375.23 \text{ kN}$$

$$y_P = 5.37 \text{ m}$$

EXAMPLE 2

FIND THE FORCE ON THE GATE



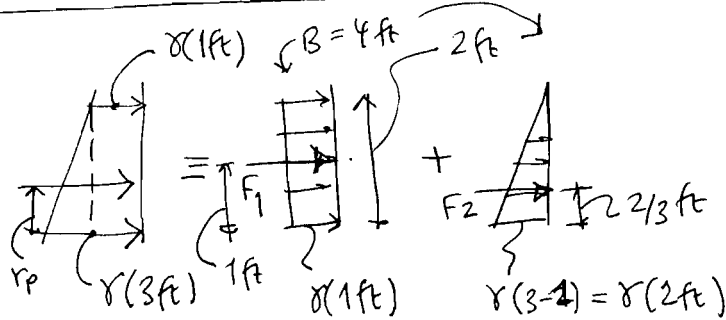
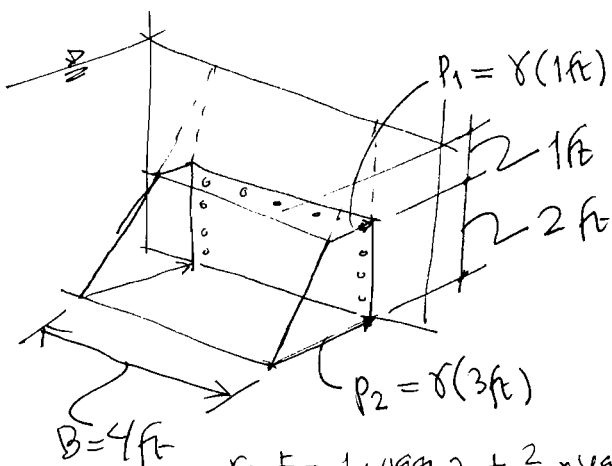
$$F = \frac{1}{2} (\gamma H) (H) B = \frac{1}{2} \gamma B H^2$$

$$\gamma = 62.4 \frac{\text{lb}}{\text{ft}^3}$$

$$F = \frac{1}{2} (62.4 \frac{\text{lb}}{\text{ft}^3}) (5 \text{ ft}) (3 \text{ ft})^2$$

$$F = 1404 \text{ lb}$$

EXAMPLE 3 - FIND FORCE ON GATE



$$F_1 = \gamma (1 \text{ ft}) (2 \text{ ft}) (4 \text{ ft}) = \gamma (8 \text{ ft}^3) = 62.4 \frac{\text{lb}}{\text{ft}^3} \times 8 \text{ ft}^3 = 499.2 \text{ lb}$$

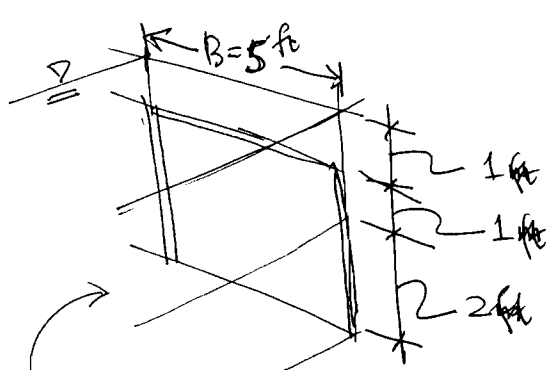
$$F_2 = \frac{1}{2} \gamma (2 \text{ ft}) (2 \text{ ft}) (4 \text{ ft}) = \gamma (8 \text{ ft}^3) = 499.2 \text{ lb}$$

$$F = F_1 + F_2 = 2 \times 499.2 \text{ lb} = 998.4 \text{ lb}$$

$$r_P \cdot F = 1 \times 499.2 + \frac{2}{3} \times 499.2$$

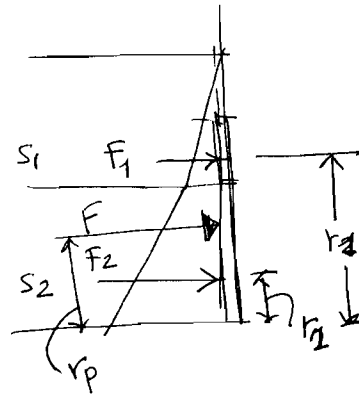
$$r_P \cdot 998.4 = 832.00 \rightarrow r_P = \frac{832.00}{998.40} = 0.833 \text{ ft}$$

# EXAMPLE 4

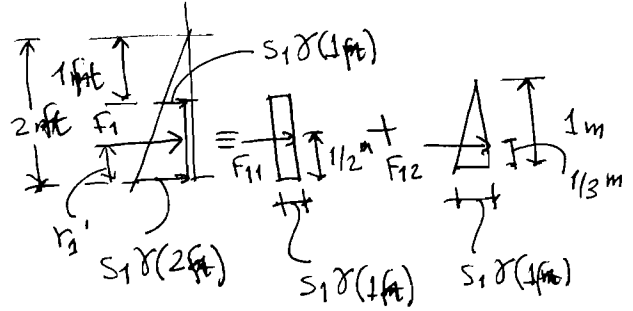


SALT WATER ( $S_2 = 1.1$ )  
 FRESH WATER ( $S_1 = 1.0$ )

$$\gamma = 62.4 \text{ lb/ft}^3$$



FOR  $F_1$



$$F_{11} = s_1 \gamma (1 \text{ ft}) (5 \text{ m}) = 5 \text{ ft}^3 \cdot s_1 \gamma$$

$$F_{12} = \frac{1}{2} s_1 \gamma (1 \text{ ft}) (5 \text{ ft}) = 2.5 \text{ ft}^3 s_1 \gamma$$

$$F_1 = F_{11} + F_{12} = 7.5 \text{ ft}^3 \cdot s_1 \gamma$$

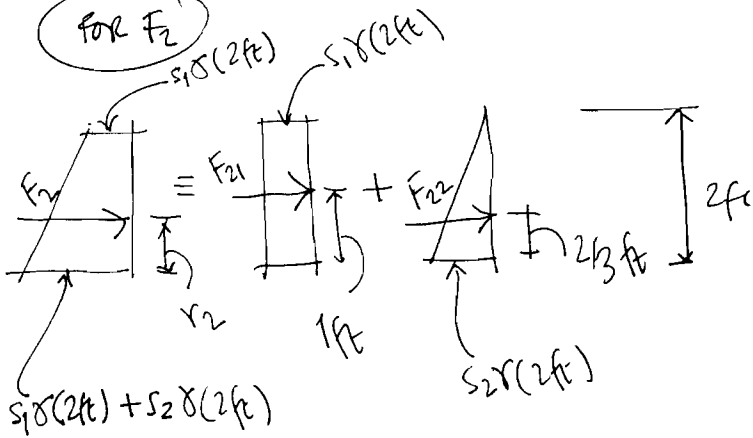
$$r_1' \times 7.5 \text{ ft}^3 \cdot s_1 \gamma = \frac{1}{2} \times 5 \text{ ft}^3 \cdot s_1 \gamma + \frac{1}{3} \times 2.5 \text{ ft}^3 \cdot s_1 \gamma$$

$$r_1' = 0.44 \text{ ft}$$

$$r_1 = r_1' + 2 \text{ ft} = 2.44 \text{ ft}$$

(11)

FOR  $F_2$



$$F_{21} = s_1 \gamma (2 \text{ ft}) (5 \text{ ft}) = 20 \text{ ft}^3 s_1 \gamma$$

$$F_{22} = \frac{1}{2} \cdot s_2 \cdot \gamma \cdot (2 \text{ ft}) (5 \text{ ft}) = 10 \text{ ft}^3 s_2 \gamma$$

$$F_2 = F_{21} + F_{22} = \gamma (20 s_1 + 10 s_2)$$

$$r_2 \cdot \gamma (20 s_1 + 10 s_2) = (1 \text{ ft}) (20 \text{ ft}^3 s_1 \gamma) + (\frac{2}{3} \text{ ft}) (10 \text{ ft}^3 s_2 \gamma)$$

$$r_2 (20 s_1 + 10 s_2) = 20 s_1 + \frac{20}{3} s_2$$

$$r_2 = \frac{20 s_1 + \frac{20}{3} s_2}{20 s_1 + 10 s_2} = \frac{20 \times 1 + \frac{20}{3} \times 1.1}{20 \times 1 + 10 \times 1.1} = 0.88 \text{ ft}$$

## TOTAL FORCE

$$F_1 = 7.5 \times 1.0 \times 62.4 = 468 \text{ lb}$$

$$F_2 = 62.4 \times (20 \times 1.0 + 10 \times 1.1) = 1934.4 \text{ lb}$$

$$F = F_1 + F_2 = 2402.4 \text{ lb}$$

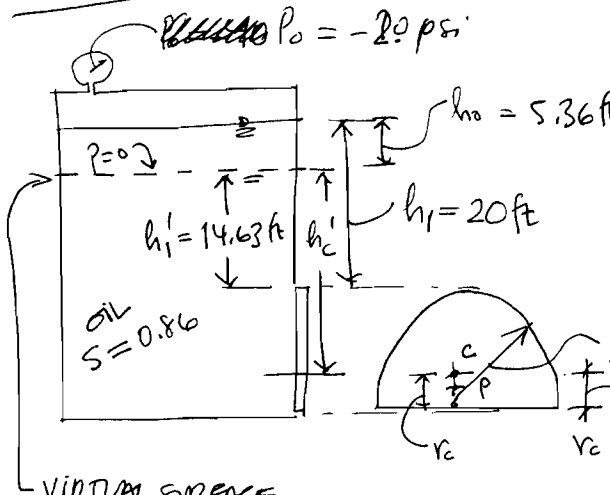
## MOMENTS

$$r_p \cdot F = r_1 F_1 + r_2 F_2$$

$$r_p \cdot 2402.4 = 2.44 \times 468 + 0.88 \times 1934.4$$

$$r_p = 1.18 \text{ ft}$$

EXAMPLE 5



with  $s = 0.86$ ,  $\gamma = 0.86 \times 62.4 \text{ lb/ft}^3 = 53.66 \text{ lb/ft}^3$

$$h_o = \frac{P_o}{\gamma} = \frac{(-20 \text{ lb/in}^2)(144 \text{ in}^2/\text{ft}^2)}{53.66 \text{ lb/ft}^3} = -5.36 \text{ ft}$$

(12)

$$h_c' = h_i + (r - r_c) = 14.63 \text{ ft} + (10 \text{ ft} - 4.24 \text{ ft}) = 20.39 \text{ ft}$$

centroidal depth

$$P_c' = \gamma h_c' = (53.66 \frac{\text{lb}}{\text{ft}^3})(20.39 \text{ ft})$$

$$P_c' = 1094.12 \text{ lb/ft}^2$$

$$F = P_c' \cdot A = (1094.12 \frac{\text{lb}}{\text{ft}^2})(157.08 \text{ ft}^2)$$

$$A = \frac{1}{2} \pi r^2 = \frac{1}{2} \cdot \pi \cdot 10^2 = 157.08 \text{ ft}^2$$

$$I_o = \frac{\pi D^4}{128} = \frac{\pi \times 20^4}{128} = 3926.99 \text{ ft}^4$$

~~F = 171865.53 lb~~

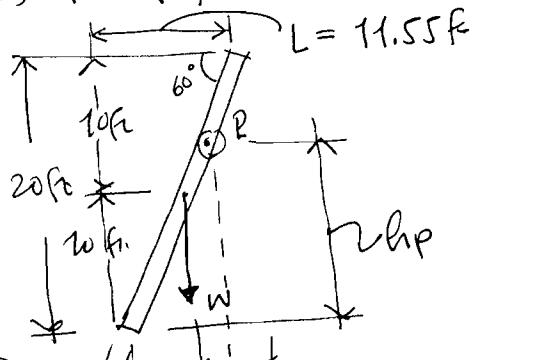
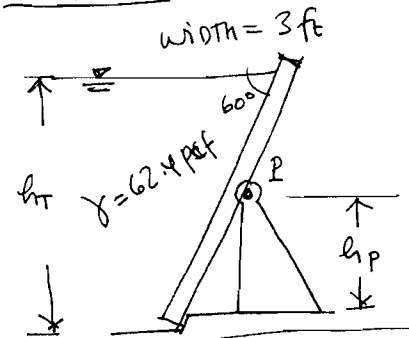
**F = 171865.53 lb**

$$y_c' = h_c' = 20.39 \text{ ft}$$

$$y_{p1} = y_c' + \frac{I_o}{y_c' A} = 20.39 \text{ ft} + \frac{3926.99 \text{ ft}^4}{(20.39 \text{ ft})(157.08 \text{ ft}^2)} = 21.61 \text{ ft}$$

or  $21.61 + 5.36 = 26.98 \text{ ft}$  from actual free surface

EXAMPLE 6. Given  $h_T = 20 \text{ ft}$ ,  $h_p = ?$  if flashboard is about to tip?

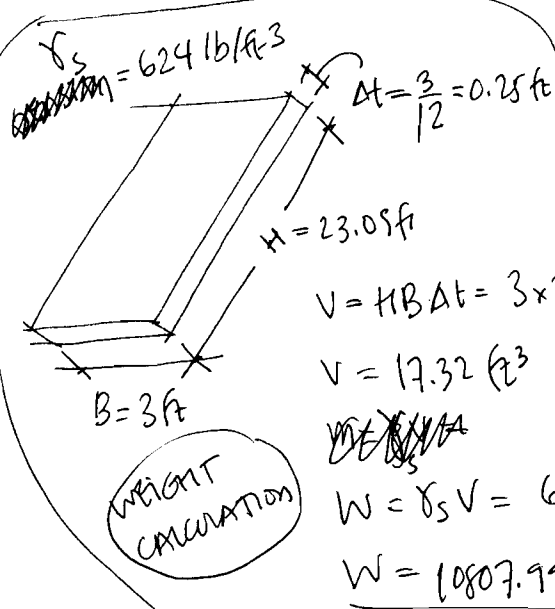


$$\sin 60^\circ = \frac{20 \text{ ft}}{H}$$

$$H = \frac{20 \text{ ft}}{\sin 60^\circ} = 23.09 \text{ ft}$$

$$\tan 60^\circ = \frac{20 \text{ ft}}{L}$$

$$L = \frac{20 \text{ ft}}{\tan 60^\circ} = 11.55 \text{ ft}$$



$$V = H B \Delta t = 3 \times 23.09 \times 0.25$$

$$V = 17.32 \text{ ft}^3$$

$$W = \gamma_s V = 624 \times 17.32$$

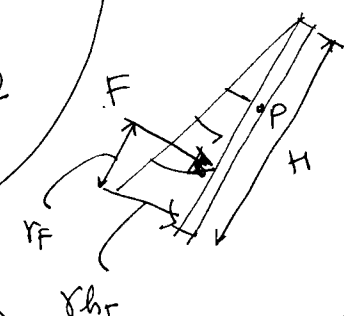
$$W = 10807.99 \text{ lb}$$

hydrostatic force

$$F = \frac{1}{2} \gamma h_T H B = \frac{1}{2} (62.4) (20) (23.09) (3)$$

$$F = 43224.48 \text{ lb}$$

$$r_f = \frac{1}{3} H = \frac{1}{3} \times 23.09 = 7.7 \text{ ft}$$

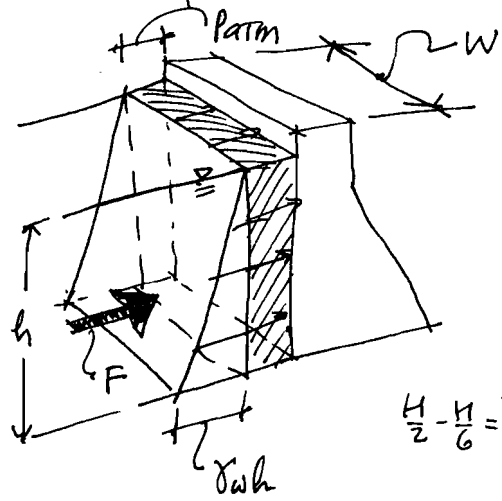
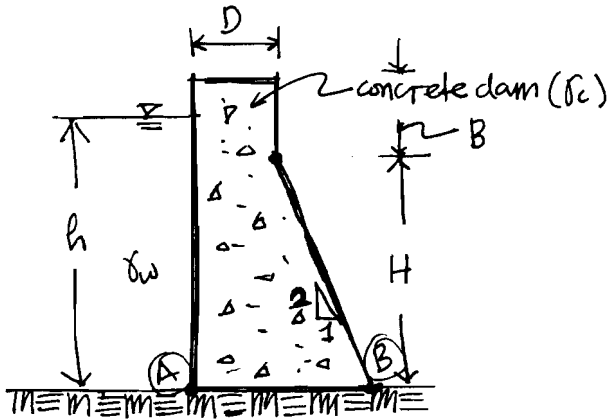


$$\sum M_P = 0, W(L' - 5.77) + F(H' - r_f) = 0$$

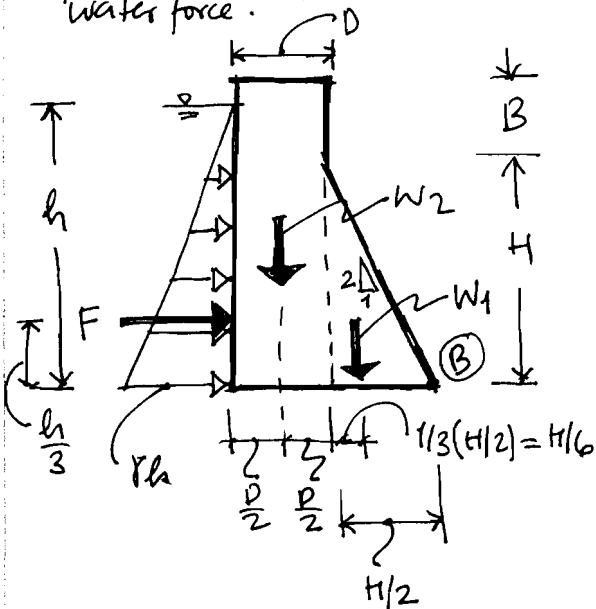
$$10807.99 \times (\frac{h_p}{\tan 60^\circ} - 5.77) + 43224.48 \times (\frac{h_p}{\sin 60^\circ} - 7.7) = 0 \Rightarrow \text{solve for } h_p = 7.04 \text{ ft}$$

$$6240 h_p - 62362.10 + 49910.77 h_p - 332828.5 = 0 \Rightarrow 56150.77 h_p = 395190.6$$

STABILITY OF A DAM: The figure shows a concrete dam (specific weight,  $\gamma_c$ ) holding water at a depth  $h$ . Determine the height  $h$  so that the dam will tip at point B. Perform the analysis on a width  $w$  of the dam.



We're tempted to add  $P_{atm}$  in calculating the force from the water on the wall. However,  $P_{atm}$  also acts on the other side of the wall, thus, using gage pressure is enough to calculate the water force.



$$\frac{H}{2} - \frac{H}{6} = \frac{3H - H}{6} = \frac{H}{3}$$

$$F = \frac{1}{2}(\gamma_w h)(h)w = \frac{1}{2}\gamma_w h^2 w$$

$$W_1 = \frac{1}{2}(h)\left(\frac{h}{2}\right)(w)\gamma_c = \frac{1}{4}\gamma_c h^2 w$$

$$W_2 = D \times (B+H) \times w \times \gamma_c = \gamma_c D w (B+H)$$

AT TILTING POINT  $\uparrow \sum M_B = 0$

$$-F \times \frac{h}{3} + W_1 \times \left(\frac{H}{2} - \frac{H}{6}\right) + W_2 \times \left(\frac{H}{2} + \frac{D}{2}\right) = 0$$

$$-\frac{1}{2}\gamma_w h^2 w \frac{h}{3} + \frac{1}{4}\gamma_c h^2 w \frac{H}{3} + \gamma_c D w (B+H) \left(\frac{H+D}{2}\right) = 0$$

$$\frac{1}{6}\gamma_w h^3 w = \gamma_c w \left(\frac{1}{12}H^3 + \frac{1}{2}D(B+H)(H+D)\right)$$

$$h^3 = \frac{\gamma_c}{\gamma_w} \left(\frac{H^3}{2} + 3D(B+H)(H+D)\right)$$

$$h = \sqrt[3]{\frac{\gamma_c}{\gamma_w} \left(\frac{H^3}{2} + 3D(B+H)(H+D)\right)}$$